# Nonlife Actuarial Models

Chapter 4 Risk Measures

# Learning Objectives

- 1. Risk measures based on premium principles
- 2. Risk measures based on capital requirements
- 3. Value-at-Risk and conditional tail expectation
- 4. Distortion functions
- 5. Proportional hazard transform

### 4.1 Uses of Risk Measures

#### Types of risks

- 1. Market risk
- 2. Credit risk
- 3. Operational risk

#### Uses of risk measures

- 1. Determination of economic capital
- 2. Determination of insurance premium
- 3. Internal risk management
- 4. External regulatory reporting

- **Definition 4.1:** A risk measure of the random loss X, denoted by  $\rho(X)$ , is a real-valued function  $\rho: X \to R$ , where R is the set of real numbers.
- As a loss random variable, X is nonnegative. Thus, the risk measure  $\rho(X)$  may be imposed to be nonnegative for the purpose of measuring insurance risks.
- However, if the purpose is to measure the risks of a portfolio of assets, X may stand for the *change* in portfolio value, which may be positive or negative. In such cases, the risk measure  $\rho(X)$  may be positive or negative.

### 4.2 Some Premium-Based Risk Measures

- Let X be a random loss. Denote  $E(X) = \mu_X$  and  $Var(X) = \sigma_X^2$ . Denote  $\varrho(X)$  as a risk measure of the loss X.
- Expected-value principle premium risk measure: premium with a loading on the expected loss, i.e.,  $\rho(X) = (1+\theta)\mu_X$ , where  $\theta \ge 0$  is the premium loading factor.
- Pure premium risk measure: no loading, i.e.,  $\theta = 0$ , so that  $\varrho(X) = \mu_X$ .
- Variance premium risk measure: loading on variance, i.e.,  $\varrho(X) = \mu_X + \alpha \sigma_X^2, \alpha \ge 0.$
- Standard-deviation risk measure: loading on standard deviation, i.e.,  $\varrho(X) = \mu_X + \alpha \sigma_X, \alpha \ge 0.$

Four axioms for coherent risk measures

Axiom 4.1 Translational invariance (T): For any loss variable X and any nonnegative constant  $a \ge 0$ ,  $\varrho(X + a) = \varrho(X) + a$ .

Axiom 4.2 Subadditivity (S): For any loss variables X and Y,  $\rho(X + Y) \leq \rho(X) + \rho(Y)$ .

Axiom 4.3 Positive homogeneity (PH): For any loss variable X and any nonnegative constant a,  $\rho(aX) = a\rho(X)$ .

Axiom 4.4 Monotonicity (M): For any loss variables X and Y such that  $X \leq Y$  under all states of nature,  $\rho(X) \leq \rho(Y)$ .

**Example 4.2:** Show that the expected-value premium risk measure satisfies Axioms S, PH and M, but not T.

**Solution:** For any risks X and Y, we have

$$\varrho(X+Y) = (1+\theta)E(X+Y)$$
  
=  $(1+\theta)E(X) + (1+\theta)E(Y)$   
=  $\varrho(X) + \varrho(Y).$ 

Thus, Axiom S holds. Now for Y = aX with  $a \ge 0$ , we have

$$\varrho(Y) = (1+\theta)\mathbf{E}(Y) = (1+\theta)\mathbf{E}(aX) = a(1+\theta)\mathbf{E}(X) = a\varrho(X),$$

which proves Axiom PH. For two risks X and Y,  $X \ge Y$  implies  $\mu_X \ge \mu_Y$ . Thus,

$$\varrho(X) = (1+\theta)\mu_X \ge (1+\theta)\mu_Y = \varrho(Y),$$

and Axiom M holds. To examine Axiom T, we consider an arbitrary constant a > 0. Note that, if  $\theta > 0$ ,

$$\varrho(X+a) = (1+\theta) \mathcal{E}(X+a) > (1+\theta) \mathcal{E}(X) + a = \varrho(X) + a.$$

Thus, Axiom T is not satisfied if  $\theta > 0$ , which implies the expected-value premium is in general not a coherent risk measure. However, when  $\theta = 0$ , Axiom T holds. Thus, the pure premium risk measure is coherent.  $\Box$ 

- It can be shown that the variance premium risk measure satisfies Axiom T, but not Axioms S, M and PH.
- On the other hand, the standard-deviation premium risk measure satisfies Axioms S, T and PH, but not Axiom M. Readers are invited to prove these results (see Exercises 4.2 and 4.3).

- The axioms of coherent risk narrow down the set of risk measures to be considered for management and regulation. However, they do not specify a unique risk measure to be used in practice.
- Some risk measures (such as the pure premium risk measure) that are coherent may not be a suitable risk measure for some reasons. Thus, the choice of which measure to use depends on additional considerations.

### 4.4 Some Capital-Based Risk Measures

#### 4.4.1 Value-at-Risk

- One of the most widely used measures of risk
- $\operatorname{VaR}_{\delta}(X)$  is the  $\delta$ -quantile of X, i.e.,

$$\operatorname{VaR}_{\delta}(X) = F_X^{-1}(\delta)$$
  
=  $\inf \{ x \in [0, \infty) : F_X(x) \ge \delta \}.$  (4.5)

Example 4.3: Find VaR<sub>δ</sub> of the following loss distributions X:
(a) *E*(λ), (b) *L*(μ, σ<sup>2</sup>), and (c) *P*(α, γ).

• Solution: For (a), from Example 2.8, we have

$$\operatorname{VaR}_{\delta} = -\frac{\log(1-\delta)}{\lambda}.$$

For (b), from Example 2.8, the VaR is

$$\operatorname{VaR}_{\delta} = \exp\left[\mu + \sigma \Phi^{-1}(\delta)\right].$$

For (c), from equation (2.38), the df of  $\mathcal{P}(\alpha, \gamma)$  is

$$F_X(x) = 1 - \left(\frac{\gamma}{x+\gamma}\right)^{\alpha},$$

so that its quantile function is

$$F_X^{-1}(\delta) = \gamma (1-\delta)^{-\frac{1}{\alpha}} - \gamma,$$

and

$$\operatorname{VaR}_{\delta} = F_X^{-1}(\delta) = \gamma \left[ (1-\delta)^{-\frac{1}{\alpha}} - 1 \right].$$

• Example 4.4: Find VaR<sub> $\delta$ </sub>, for  $\delta = 0.95$ , 0.96, 0.98 and 0.99, of the following discrete loss distribution

$$X = \begin{cases} 100, & \text{with prob } 0.02, \\ 90, & \text{with prob } 0.02, \\ 80, & \text{with prob } 0.04, \\ 50, & \text{with prob } 0.12, \\ 0, & \text{with prob } 0.80. \end{cases}$$

• Solution: As X is discrete, we use the definition of VaR in equation (4.5). The df of X is plotted in Figure 4.1. The dotted horizontal lines correspond to the probability levels 0.95, 0.96, 0.98 and 0.99. Note that the df of X is a step function. For VaR<sub> $\delta$ </sub> we require the value of X corresponding to the probability level equal to or next-step higher than  $\delta$ . Thus, VaR<sub> $\delta$ </sub> for  $\delta = 0.95$ , 0.96, 0.98 and 0.99, are, respectively, 80, 80, 90 and 100.



#### 4.4.2 Conditional Tail Expectation

- VaR does not use any information about the loss distribution beyond the cut-off point.
- Conditional tail expectation, denoted by  $CTE_{\delta}(X)$ , rectifies this.
- Definition:

$$CTE_{\delta}(X) = E[X | X > VaR_{\delta}(X)]$$
(4.10)

• When X is continuous, we have

$$CTE_{\delta} = E(X \mid X > VaR_{\delta}) = \frac{1}{1-\delta} \int_{VaR_{\delta}}^{\infty} x f_X(x) \, dx.$$
 (4.17)

• Using change of variable  $\xi = F_X(x)$ , the integral above can be written as

$$\int_{\operatorname{VaR}_{\delta}}^{\infty} x f_X(x) \, dx \quad = \quad \int_{\operatorname{VaR}_{\delta}}^{\infty} x \, dF_X(x)$$

$$= \int_{\delta}^{1} \operatorname{VaR}_{\xi} d\xi, \qquad (4.18)$$

which implies

$$CTE_{\delta} = \frac{1}{1-\delta} \int_{\delta}^{1} VaR_{\xi} d\xi.$$
(4.19)

- Thus,  $CTE_{\delta}$  can be interpreted as the *average* of the VaRs exceeding VaR<sub> $\delta$ </sub>. We call the expression on the RHS of (4.19) the **Tail VaR**, denoted as  $TVaR_{\delta}$ .
- When X is not continuous, we use the following formula

$$CTE_{\delta} = \frac{(\bar{\delta} - \delta) \operatorname{VaR}_{\delta} + (1 - \bar{\delta}) \operatorname{E}(X \mid X > \operatorname{VaR}_{\delta})}{1 - \delta}, \qquad (4.22)$$

where

$$\bar{\delta} = \Pr(X \le \operatorname{VaR}_{\delta}). \tag{4.21}$$

#### Remarks

- VaR is not a coherent risk measure. It violates the subadditivity axiom.
- CTE is a coherent risk measure.

**Example 4.6:** Calculate  $CTE_{\delta}$  for the loss distribution given in Example 4.4, for  $\delta = 0.95$ , 0.96, 0.98 and 0.99. Also, calculate TVaR corresponding to these values of  $\delta$ .

**Solution:** As X is not continuous we use equation (4.22) to calculate  $CTE_{\delta}$ . Note that  $VaR_{0.95} = VaR_{0.96} = 80$ . For  $\delta = 0.95$ , we have  $\bar{\delta} = 0.96$ . Thus,

$$E(X | X > VaR_{0.95} = 80) = \frac{90(0.02) + 100(0.02)}{1 - 0.96} = 95,$$

so that from equation (4.22) we obtain

$$CTE_{0.95} = \frac{(0.96 - 0.95)80 + (1 - 0.96)95}{1 - 0.95} = 92.$$

For  $\delta = 0.96$ , we have  $\overline{\delta} = 0.96$ , so that

$$CTE_{0.96} = E(X | X > VaR_{0.96} = 80) = 95.$$

For TVaR<sub> $\delta$ </sub>, we use equation (4.23) to obtain

TVaR<sub>0.95</sub> = 
$$\frac{1}{1 - 0.95} \int_{0.95}^{1} \text{VaR}_{\xi} d\xi$$
  
=  $\frac{1}{0.05} [(80)(0.01) + (90)(0.02) + (100)(0.02)]$   
= 92,

and

$$TVaR_{0.96} = \frac{1}{1 - 0.96} \int_{0.96}^{1} VaR_{\xi} d\xi = \frac{1}{0.04} \left[ (90)(0.02) + (100)(0.02) \right] = 95.$$

For  $\delta = 0.98$ , we have  $\overline{\delta} = 0.98$ , so that

$$CTE_{0.98} = E(X \mid X > VaR_{0.98} = 90) = \frac{(100)(0.02)}{1 - 0.98} = 100,$$

which is also the value of TVaR<sub>0.98</sub>. Finally, for  $\delta = 0.99$ , we have  $\overline{\delta} = 1$  and VaR<sub>0.99</sub> = 100, so that  $\text{CTE}_{0.99} = \text{VaR}_{0.99} = 100$ . On the other hand, we have

TVaR<sub>0.99</sub> = 
$$\frac{1}{1 - 0.99} \int_{0.99}^{1} \text{VaR}_{\xi} d\xi = \frac{(100)(0.01)}{0.01} = 100.$$

### 4.5 More Premium-Based Risk Measure

#### 4.5.1 Proportional hazard transform and risk-adjusted premium

• The premium-based risk measures define risk based on a loading of the expected loss. The expected loss  $\mu_X$  of a continuous random loss X can be written as

$$\mu_X = \int_0^\infty S_X(x) \, dx. \tag{4.27}$$

- Thus, instead of adding a *loading* to  $\mu_X$  to obtain a premium we may *re-define* the distribution of the loss.
- Suppose  $\tilde{X}$  is distributed with sf  $S_{\tilde{X}}(x) = [S_X(x)]^{\frac{1}{\rho}}$ , where  $\rho \ge 1$ , then the mean of  $\tilde{X}$  is

$$E(\tilde{X}) = \mu_{\tilde{X}} = \int_0^\infty S_{\tilde{X}}(x) \, dx = \int_0^\infty \left[ S_X(x) \right]^{\frac{1}{\rho}} \, dx. \tag{4.28}$$

- The parameter  $\rho$  is called the **risk-aversion index**.
- The distribution of  $\tilde{X}$  is called the **proportional hazard (PH)** transform of the distribution of X with parameter  $\rho$ .
- If we denote  $h_X(x)$  and  $h_{\tilde{X}}(x)$  as the hf of X and  $\tilde{X}$ , respectively, then from equations (2.2) and (2.3), we have

$$h_{\tilde{X}}(x) = -\frac{1}{S_{\tilde{X}}(x)} \left( \frac{dS_{\tilde{X}}(x)}{dx} \right) = -\frac{1}{\rho} \left( \frac{[S_X(x)]^{\frac{1}{\rho} - 1} S'_X(x)}{[S_X(x)]^{\frac{1}{\rho}}} \right) = -\frac{1}{\rho} \left( \frac{S'_X(x)}{S_X(x)} \right) = \frac{1}{\rho} h_X(x),$$
(4.30)

so that the hf of  $\tilde{X}$  is proportional to the hf of X.

• As  $\rho \geq 1$ , the hf of  $\tilde{X}$  is less than that of X, implying that  $\tilde{X}$  has a thicker tail than that of X. Also,  $S_{\tilde{X}}(x) = [S_X(x)]^{\frac{1}{\rho}}$  declines slower than  $S_X(x)$  so that  $\mu_{\tilde{X}} > \mu_X$ , the difference of which represents the loading.

**Example 4.7:** If  $X \sim \mathcal{E}(\lambda)$ , find the PH transform of X with parameter  $\rho$  and the risk-adjusted premium.

**Solution:** The sf of X is  $S_X(x) = e^{-\lambda x}$ . Thus, the sf of the PH transform is  $S_{\tilde{X}}(x) = (e^{-\lambda x})^{\frac{1}{\rho}} = e^{-\frac{\lambda}{\rho}x}$ , which implies  $\tilde{X} \sim \mathcal{E}(\lambda/\rho)$ . Hence, the riskadjusted premium is  $E(\tilde{X}) = \rho/\lambda \ge 1/\lambda = E(X)$ .

**Example 4.8:** If  $X \sim \mathcal{P}(\alpha, \gamma)$  with  $\alpha > 1$ , find the PH transform of X with parameter  $\rho \in [1, \alpha)$  and the risk-adjusted premium.

#### **Solution:** The sf of X is

$$S_X(x) = \left(\frac{\gamma}{\gamma+x}\right)^{\alpha},$$

with mean

$$\mu_X = \frac{\gamma}{\alpha - 1}.$$

The sf of  $\tilde{X}$  is

$$S_{\tilde{X}}(x) = \left[S_X(x)\right]^{\frac{1}{\rho}} = \left(\frac{\gamma}{\gamma+x}\right)^{\frac{\alpha}{\rho}},$$

so that  $\tilde{X} \sim \mathcal{P}(\alpha/\rho, \gamma)$ . Hence, the mean of  $\tilde{X}$  (the risk-adjusted premium) is

$$\mu_{\tilde{X}} = \frac{\gamma}{\frac{\alpha}{\rho} - 1} = \frac{\rho\gamma}{\alpha - \rho} > \frac{\gamma}{\alpha - 1} = \mu_X.$$





## 4.6 The Distortion-Function Approach

The **distortion function** is a mathematical device to construct risk measures.

**Definition 4.2:** A distortion function is a nondecreasing function  $g(\cdot)$  satisfying g(1) = 1 and g(0) = 0.

- Suppose X is a loss random variable with sf  $S_X(x)$ . As the distortion function  $g(\cdot)$  is nondecreasing and  $S_X(x)$  is a nonincreasing function of x,  $g(S_X(x))$  is a nonincreasing function of x.
- Together with the property that  $g(S_X(0)) = g(1) = 1$  and  $g(S_X(\infty)) = g(0) = 0$ ,  $g(S_X(x))$  is a well defined sf over the support  $[0, \infty)$ .

- We denote the random variable with this sf as  $\tilde{X}$ , which may be interpreted as a risk-adjusted loss random variable, and  $g(S_X(x))$  is the risk adjusted sf.
- We further assume that  $g(\cdot)$  is concave down (i.e.,  $g''(x) \leq 0$  if the derivative exists).

**Definition 4.3:** Let X be a nonnegative loss random variable. The distortion risk measure based on the distortion function  $g(\cdot)$ , denoted by  $\rho(X)$ , is defined as

$$\varrho(X) = \int_0^\infty g(S_X(x)) \, dx. \tag{4.42}$$

Thus, the distortion risk measure  $\rho(X)$  is the mean of the risk-adjusted loss  $\tilde{X}$ . The class of distortion risk measures include the following measures we have discussed.

#### Pure premium risk measure

It can be seen easily by defining

$$g(u) = u, \tag{4.43}$$

which satisfies the conditions g(0) = 0 and g(1) = 1, and  $g(\cdot)$  is nondecreasing. Now

$$\varrho(X) = \int_0^\infty g(S_X(x)) \, dx = \int_0^\infty S_X(x) \, dx = \mu_X, \tag{4.44}$$

which is the pure premium risk measure.

**Proportional hazard risk-adjusted premium risk measure** This can be seen by defining

$$g(u) = u^{\frac{1}{\rho}}, \qquad \rho \ge 1.$$
 (4.45)

#### VaR risk measure

For  $VaR_{\delta}$  we define the distortion function as

$$g(S_X(x)) = \begin{cases} 0, & \text{if } 0 \le S_X(x) < 1 - \delta, \\ 1, & \text{if } 1 - \delta \le S_X(x) \le 1, \end{cases}$$
(4.46)

which is equivalent to

$$g(S_X(x)) = \begin{cases} 0, & \text{if } x > \text{VaR}_{\delta}, \\ 1, & \text{if } 0 \le x \le \text{VaR}_{\delta}. \end{cases}$$
(4.47)

Hence,

$$\varrho(X) = \int_0^\infty g(S_X(x)) \, dx = \int_0^{\operatorname{VaR}_\delta} \, dx = \operatorname{VaR}_\delta. \tag{4.48}$$

#### CTE risk measure

For  $CTE_{\delta}$  we define the distortion function as (subject to the condition

#### X is continuous)

$$g(S_X(x)) = \begin{cases} \frac{S_X(x)}{1-\delta}, & \text{if } 0 \le S_X(x) < 1-\delta, \\ 1, & \text{if } 1-\delta \le S_X(x) \le 1, \end{cases}$$
(4.49)

which is equivalent to

$$g(S_X(x)) = \begin{cases} \frac{S_X(x)}{1-\delta}, & \text{if } x > x_\delta, \\ 1, & \text{if } 0 \le x \le x_\delta. \end{cases}$$
(4.50)

**Theorem 4.1:** Let  $g(\cdot)$  be a concave-down distortion function. The risk measure of the loss X defined in equation (4.42) is translational invariant, monotonic, positively homogeneous and subadditive, and is thus coherent.